

Adaptive Real-Time Computation for Prompt Localization of Transients

Marion Sudvarg (msudvarg@wustl.edu, www.sudvarg.com)

with Ye Htet, Jeremy Buhler, Roger Chamberlain, Chris Gill, Jim Buckley, and Wenlei Chen for the APT collaboration



The Astro2020 decadal survey identified “time-domain and multi-messenger” programs as the highest-priority sustaining activity for space-based missions.

“It is essential to maintain and expand space-based time-domain and follow-up facilities in space.”

Engineering National Academies of Sciences and Medicine. Pathways to Discovery in Astronomy and Astrophysics for the 2020s. The National Academies Press, Washington, DC, 2023

Key Motivation

- Need to localize promptly to capture early follow-up observations.
- Can we perform localization on board space-based instrument?
- Limited computational capacity due to radiation hardening, size, weight, and power constraints, etc.
- But if we *can*, we are able to immediately communicate to space-based and ground-based follow-up instruments!

Let’s reason about real-time localization of transients in a principled way.

What do we want?

- Ability to localize transients in real-time aboard space-based hardware.
- Make hard guarantees about latency using approaches from real-time, cyber-physical, and safety-critical computing.
- Adjust computation for latency guarantees in the face of *dynamic workloads* and *deadlines*.

Dynamic Workloads:

- Amount of data to process may depend on transient’s flux, duration, etc.
- Algorithms may change depending on quality of data, other characteristics.

Dynamic Deadlines:

- How long do we have access to communication network?
- Which follow-up instruments are available?
- How far away are they (communication latency)?
- How exciting is this transient?
- How much time do we have for meaningful observations?

Computational requirements and timing constraints may not be known a priori!

Let’s characterize the *shape* of the computation *offline* so that we can *adapt online* to achieve expected Pareto-optimal results within the imposed deadline

Case Study: Real-Time GRB Localization Aboard APT

The Advanced Particle-astrophysics Telescope (APT) is a future space-based observatory that will detect and localize GRBs in real time to enable concurrent, multi-messenger observations from any direction with minimal delay. For these soft transients, Compton-regime gammas should dominate the emission spectrum. We have therefore designed a parallel computational pipeline for real-time multi-Compton reconstruction and GRB localization. To keep latency low, this will execute fully onboard the instrument, which imposes significant size, weight, and power constraints.



<https://adapt.physics.wustl.edu/>

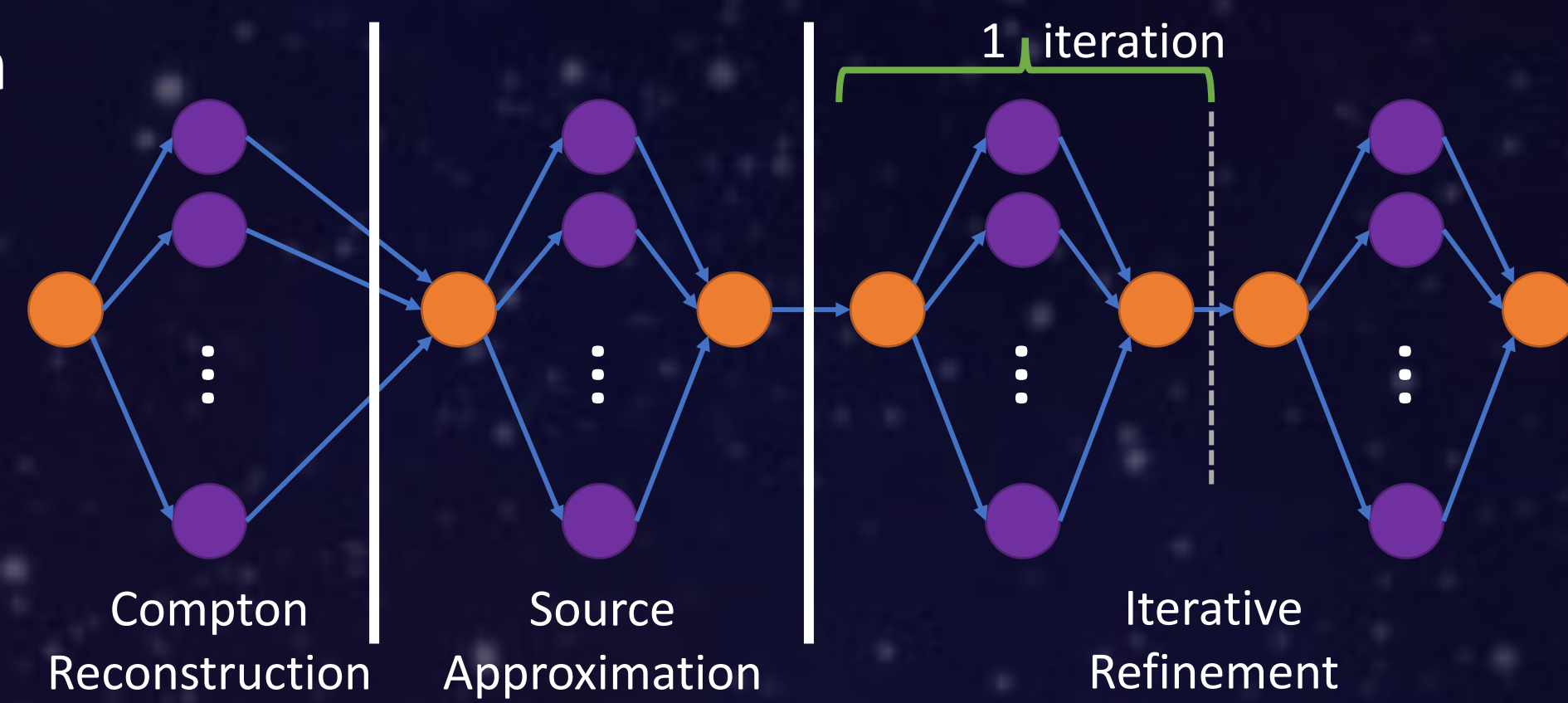
Please visit poster #255, “A Computational Pipeline for Prompt Gamma-Ray Burst Localization Aboard APT and ADAPT”



APT simulation model from:

W. Chen, et al. “The Advanced Particle-astrophysics Telescope: Simulation of the Instrument Performance for Gamma-Ray Detection.” In PoS(CR2021), volume 395, pages 590:1–590:9, July 2021.

Mission Details



Challenge: Dynamic Workloads and Deadlines

Every GRB is unique!
 Brightness ($10^3 - 10^6$ incident gamma rays)
 Spectral energy distributions
 Initial burst durations (10 milliseconds – 20 minutes)

Workload depends on
 The number of gamma rays entering the detector
 Their physical interactions

Deadline may depend on
 The duration of the burst
 Availability of follow-up instruments

How can we *adapt and compress* the computational pipeline to maximize localization accuracy even for bright transients while guaranteeing short deadlines?

3 Quantify Response Time

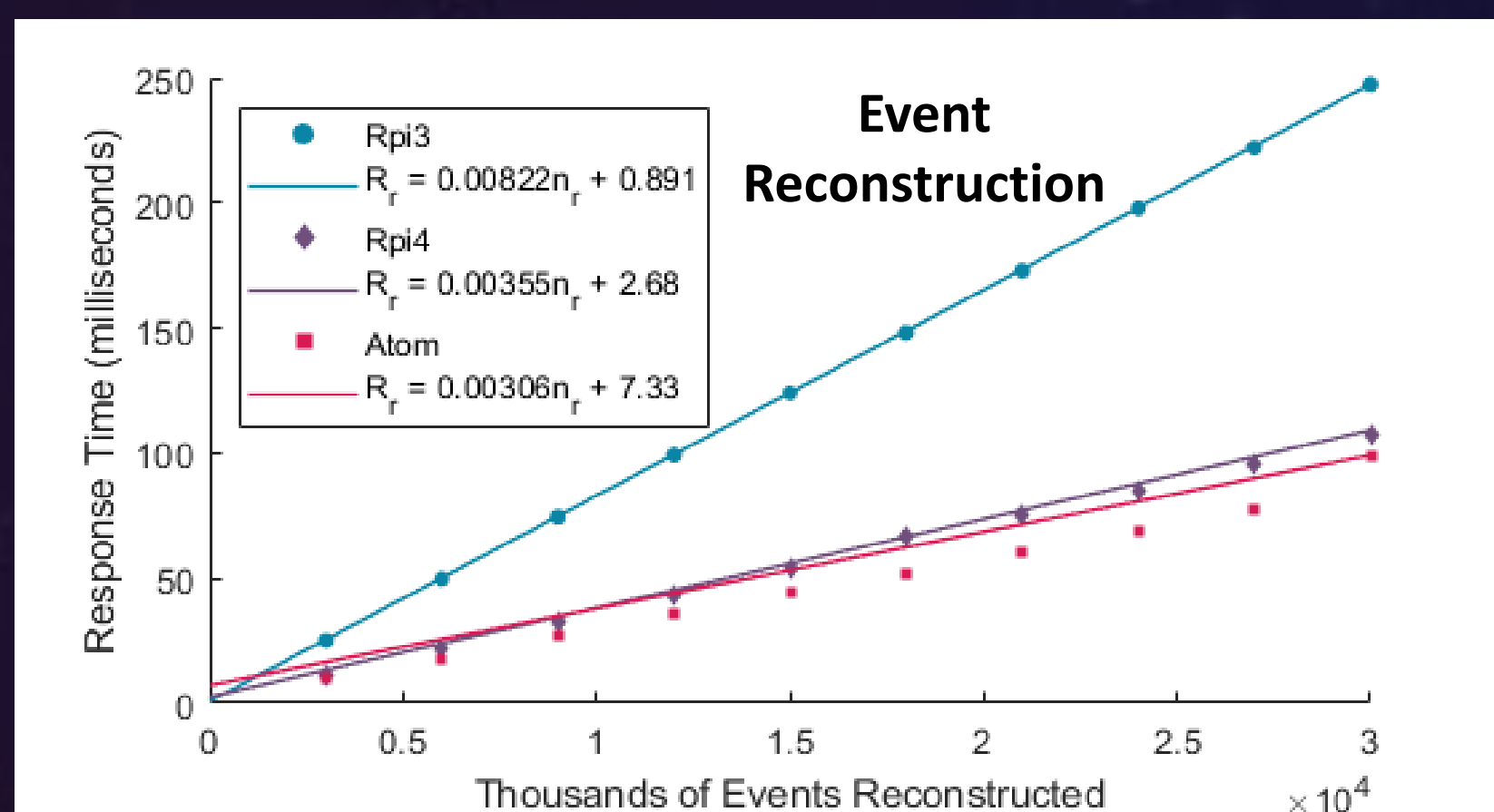
For a highly-parallel fork-join task like GRB localization, worst-case response time can be quantified by decomposing it into constituent subtasks, then profiling execution times as functions of input parameters

$$\text{Response Time Expression } R = \sum_{\tau_i \in S} C_i + \sum_{\tau_i \in S} \frac{C_i}{n}$$

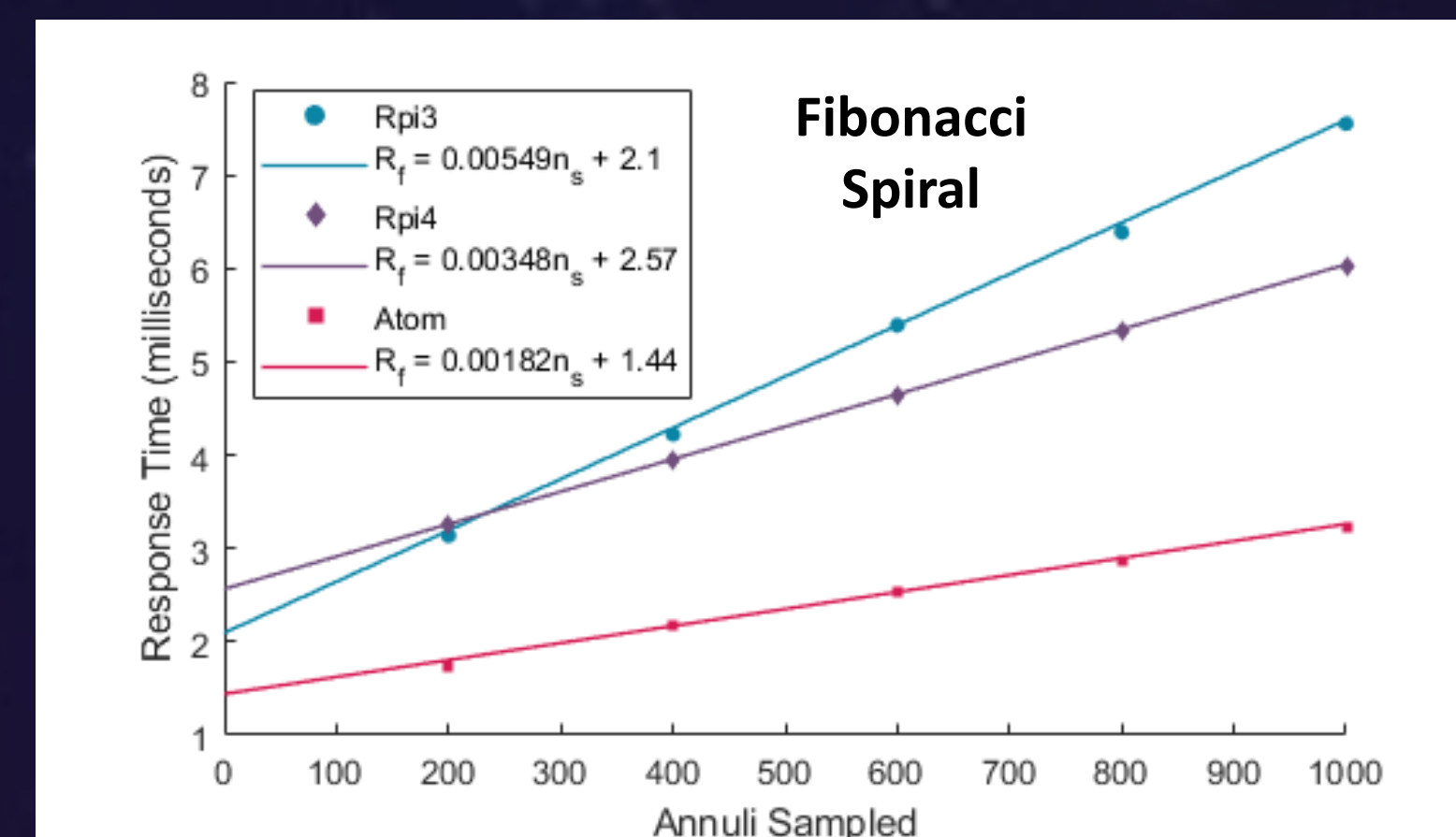
- τ_i : a subtask
- S : the set of sequential subtasks
- P : the set of highly-parallel subtasks
- $\{a_j\}$: the set of adjustable workload parameters
- $C_i(\{a_j\})$: the execution time of τ_i on a single core given a set of assigned parameter values
- $R_i(\{a_j\})$: the response time of the task for the given set of assigned parameter values
- n : the number of CPU cores

Platform	Abbr.	CPU	Freq
Raspberry Pi 3B+	RPi3	4-Core Cortex-A53	700MHz**
Raspberry Pi 4B	RPi4	4-Core Cortex-A72	600MHz**
Winsystems EBC-C413*	Atom	4-Core Intel Atom E3845	1.92GHz

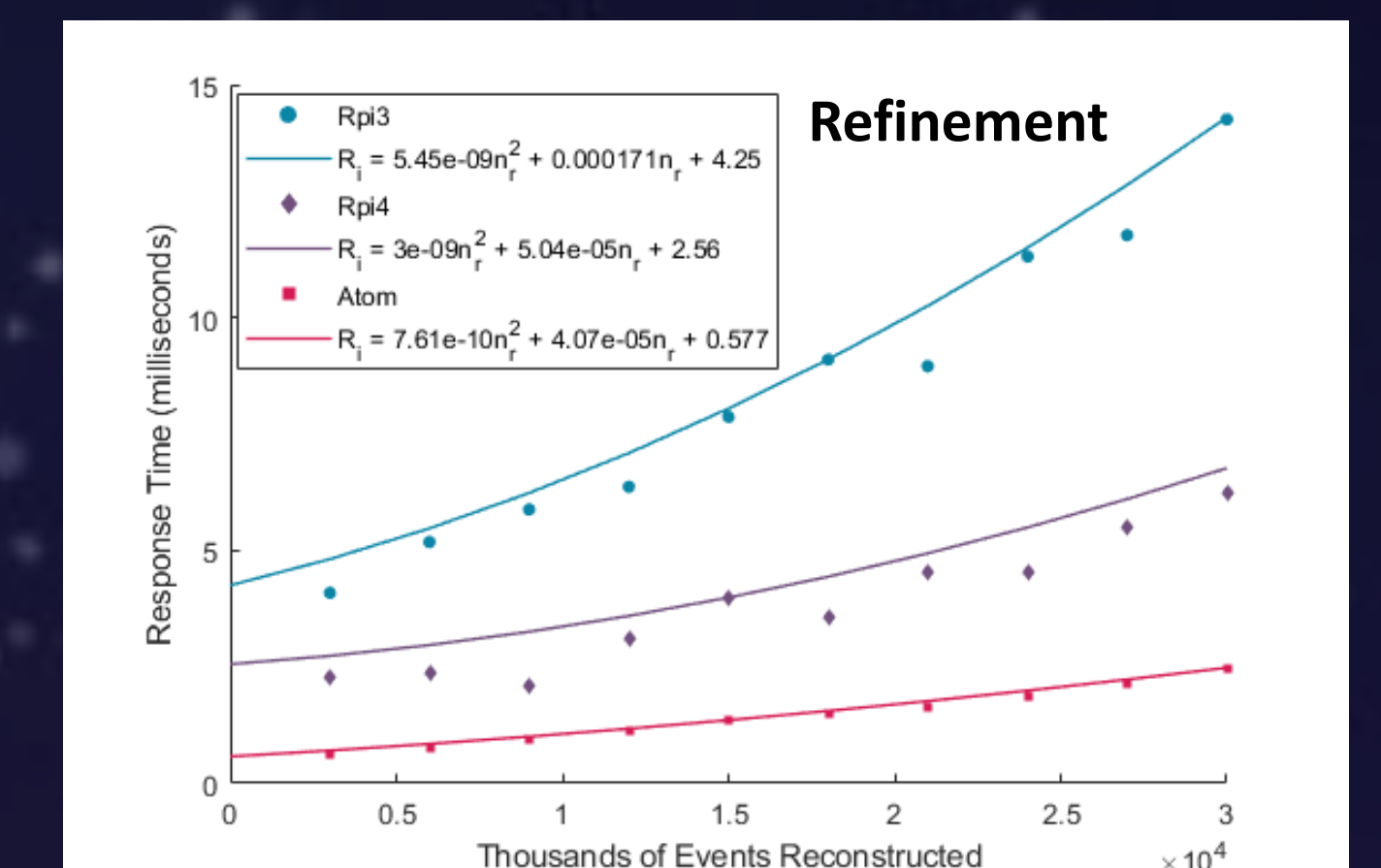
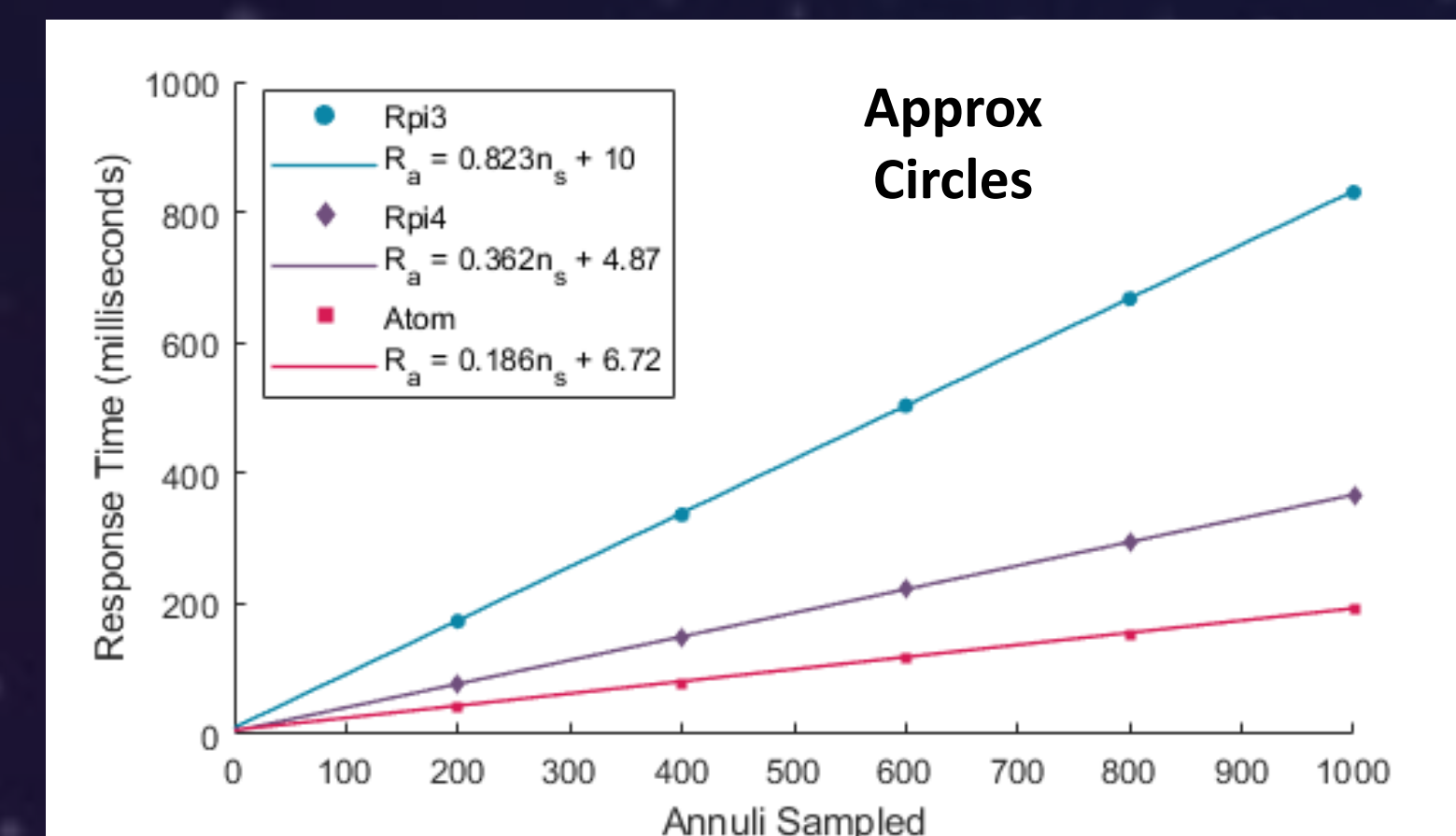
* Will fly on APT’s high-altitude Antarctic demonstrator (ADAPT)
 ** Lower frequencies prevent thermal throttling and instability in power-constrained environments



Reconstruction is linear in the number of Compton events selected



Both approximation techniques are linear in the number of Compton rings sampled



Each iteration of refinement is quadratic in the number of Compton events selected

4 Generate Pareto-Optimal Surface

Sort candidate states by response time, discarding any with a higher loss than a previous state. We are left with just those state for which *more* execution results in *better* expected outcome.



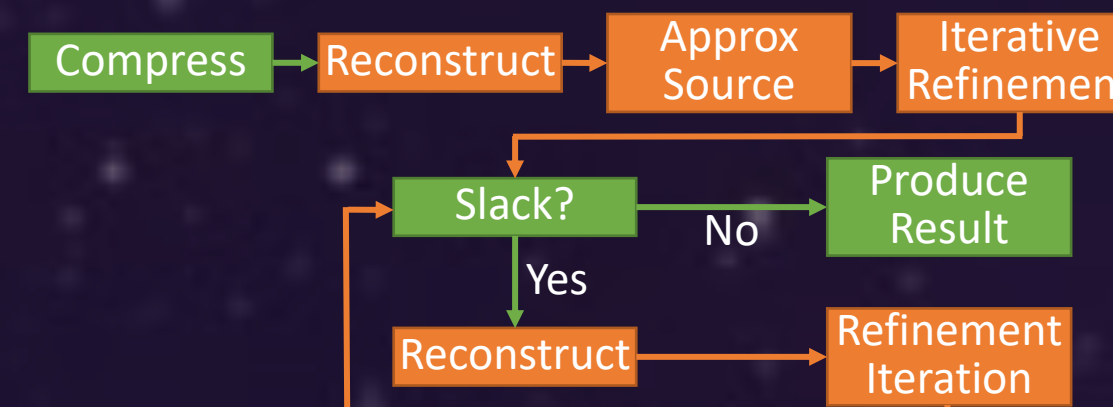
5 Online Solution Search

When a transient appears, determine workload (based on quantity of data) and deadline, then adapt computational parameters to Pareto-optimal selection

1. Binary search over Pareto-optimal subset for best set of parameters not exceeding deadline
2. Data structure includes gradients for linear interpolation/extrapolation to exactly meet deadline (we use log-linear interpolation)

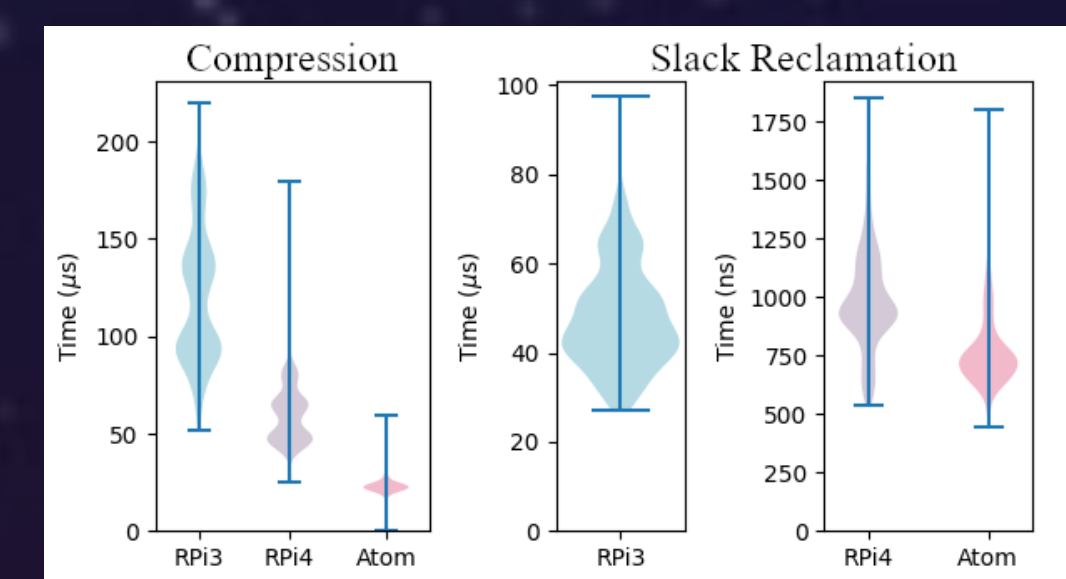
6 Reclaim Slack

We use worst-case response times to guarantee we meet dynamic deadlines. But if we complete early, slack time remains. We can reclaim slack via further computation



Low Overheads

By constructing a Pareto-optimal surface *offline*, we can adjust *online* with low overhead. Keeps CPU free for the actual science!



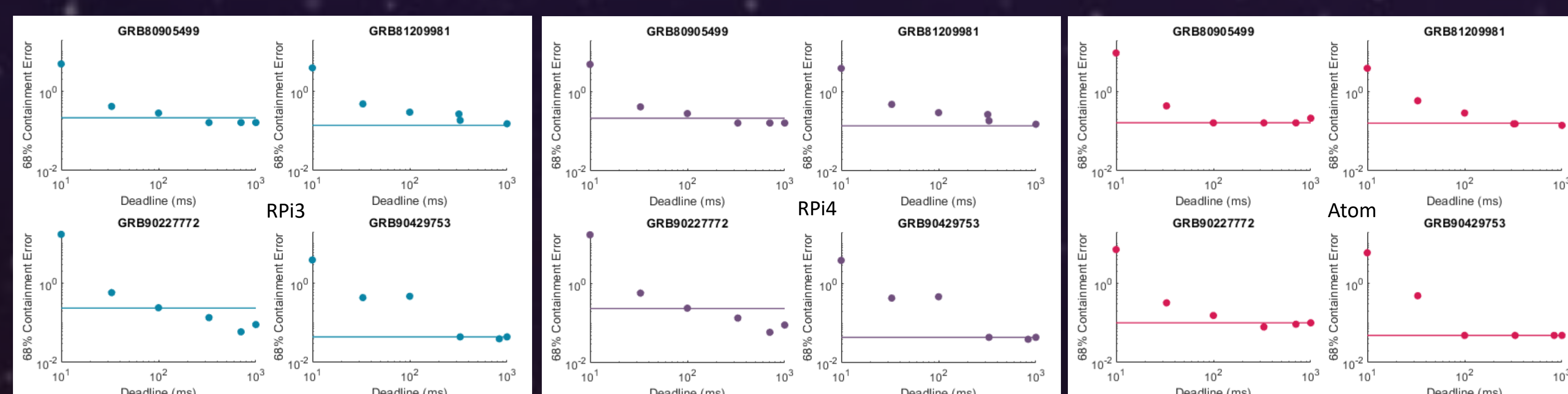
Localization Results

GEANT-based simulation of 4 short GRBs observed by Fermi GBM with fluence and Band function spectral parameters taken from

L. Nava, G. Ghirlanda, G. Ghisellini, and A. Celotti, “Spectral properties of 438 GRBs detected by Fermi GBM,” *Astronomy & Astrophysics*, vol. 530, p. A21, Apr. 2011.

Tested localization accuracy when adapting to short imposed deadlines

Our approach enables sub-degree localization even for 33ms deadlines!



Final Thoughts

More details can be found in our paper:

Marion Sudvarg et al. “Parameterized Workload Adaptation for Fork-Join Tasks with Dynamic Workloads and Deadlines.” *RTCSA 2023*.

These techniques are not just for GRBs!

Can we apply to search for optical counterparts of FRBs?

Let’s talk about how these ideas can extend to your application!

Let’s also talk about accelerating your application on heterogeneous multicore, GPU and FPGA architectures

Please also visit poster #226, “Accelerating Compton Imaging of Astrophysical Sources in Python”